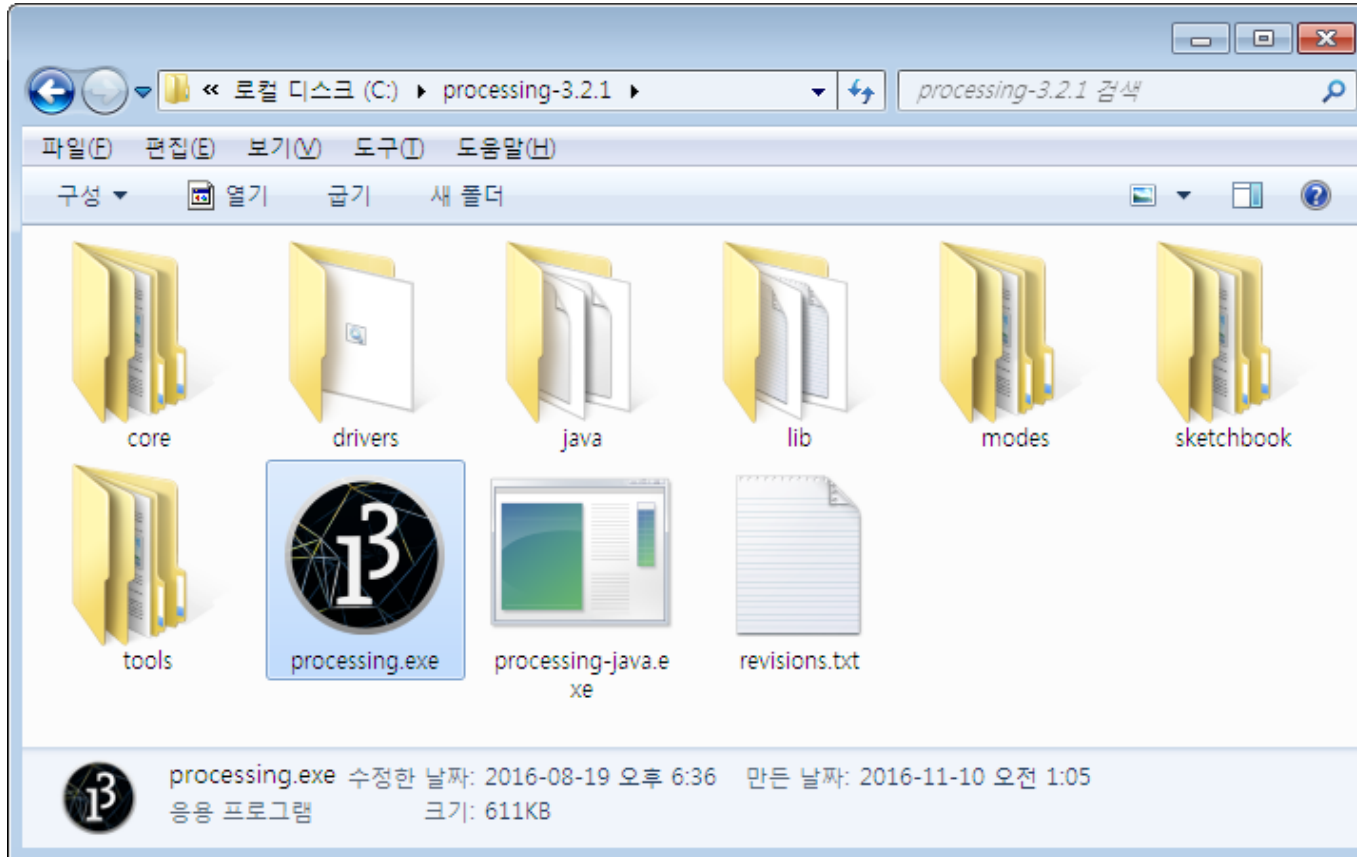


프로세싱

광운대학교 로봇학부
박광현

- C:\#processing-3.2.1 폴더



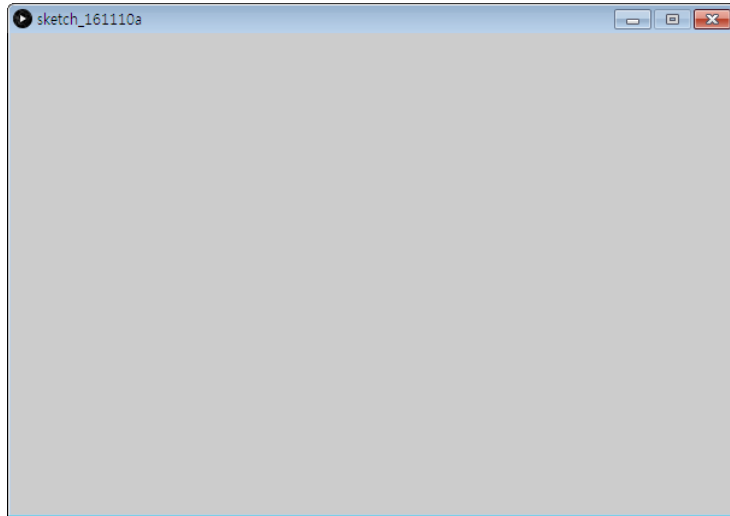
창 나타내기

```
size(600, 400);
```

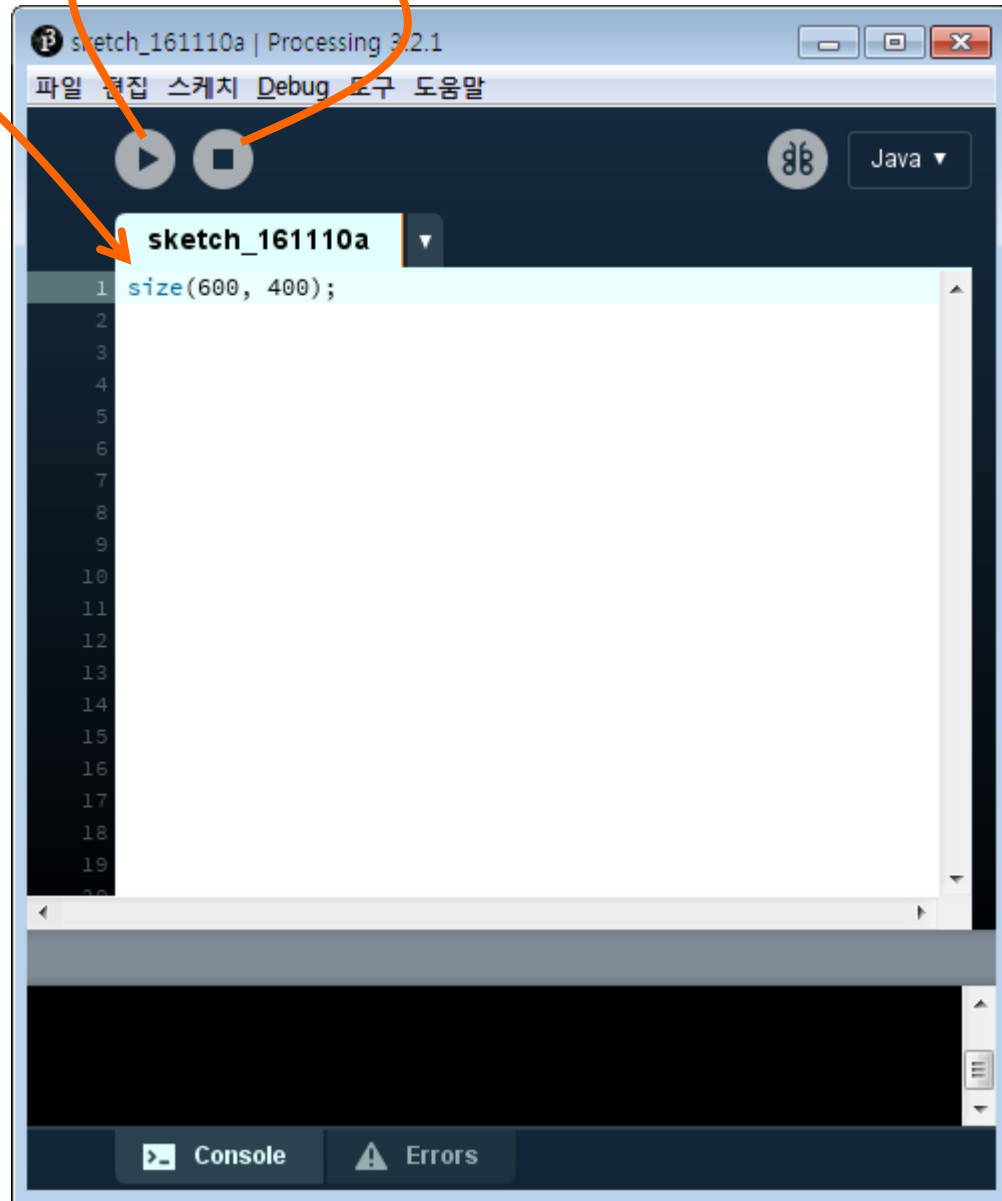
폭 높이

600

400



실행 정지



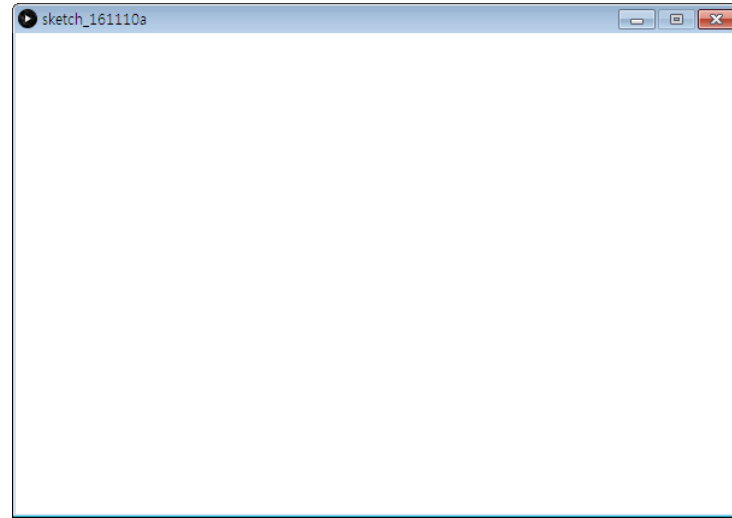
도형 그리기

배경 칠하기

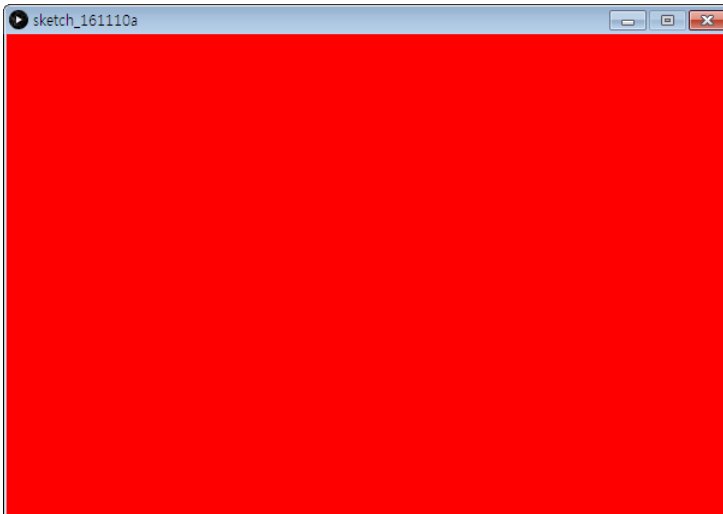
5

```
size(600, 400);  
background(255, 255, 255);
```

R G B



```
size(600, 400);  
background(255, 0, 0);
```



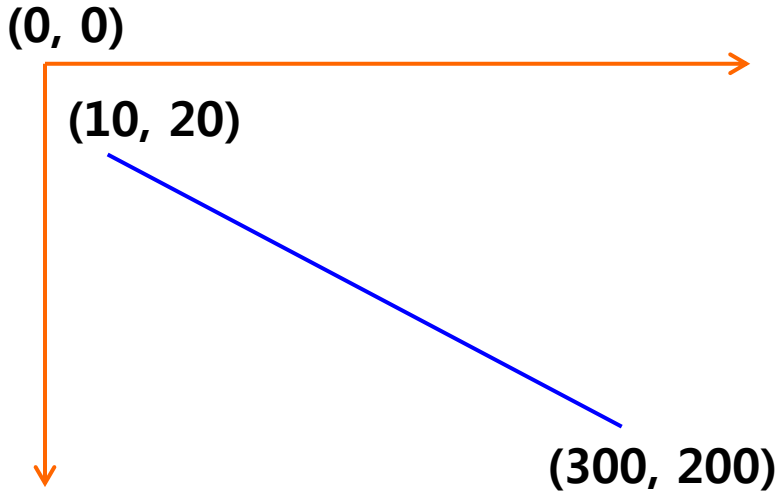
```
size(600, 400);  
background(255, 122, 0);
```



선 그리기

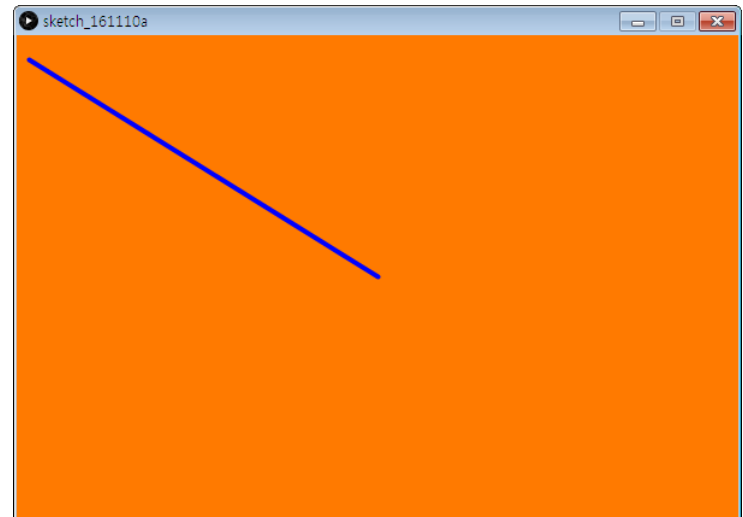
```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
line(10, 20, 300, 200);
```

→ 선 색깔 (그리기 전에 설정한다)



```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
line(10, 20, 300, 200);
```

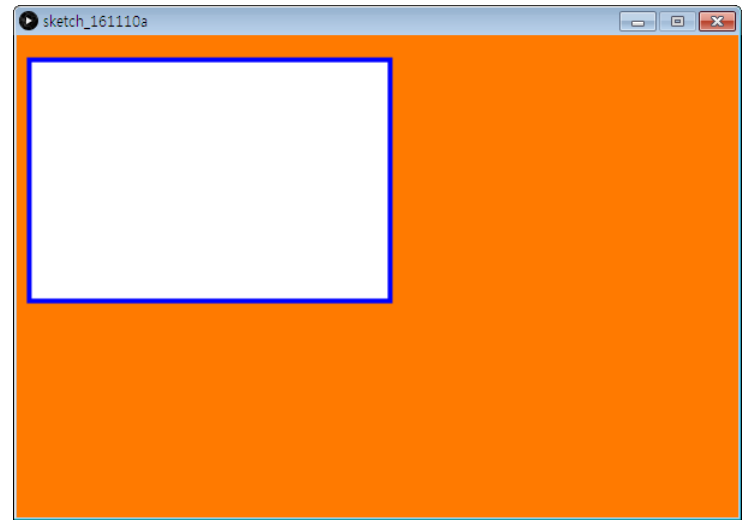
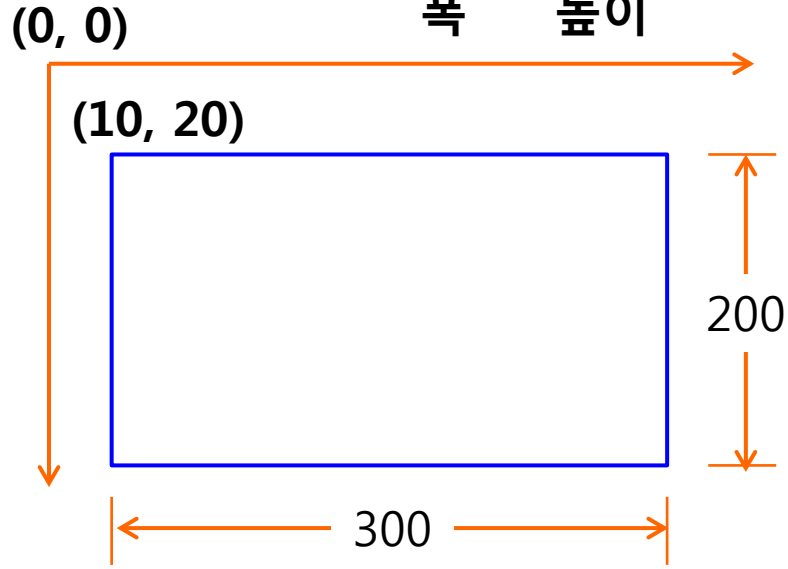
→ 선 두께 (픽셀) (그리기 전에 설정한다)



직사각형 그리기

```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
rect(10, 20, 300, 200);
```

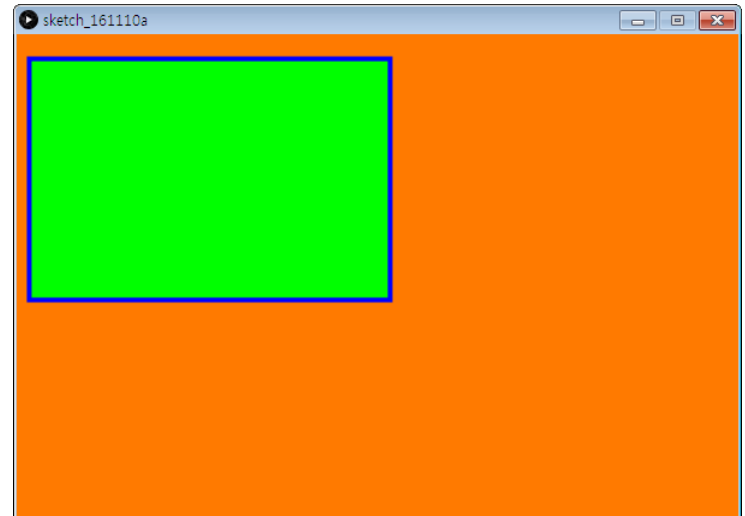
폭 높이



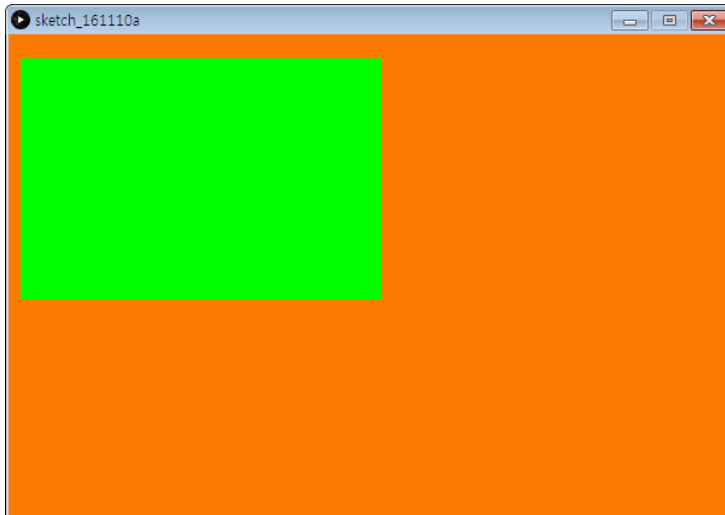
색깔 채우기

```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
rect(10, 20, 300, 200);
```

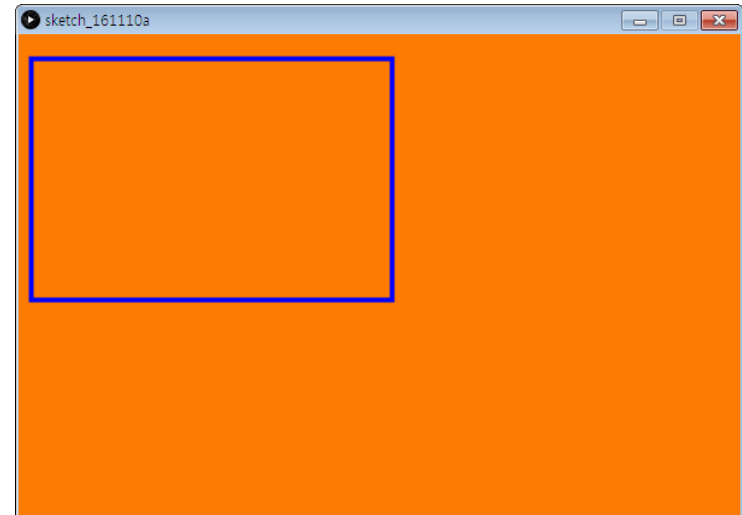
→ 채우기 색깔 (그리기 전에 설정한다)



```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
noStroke();  
rect(10, 20, 300, 200);
```



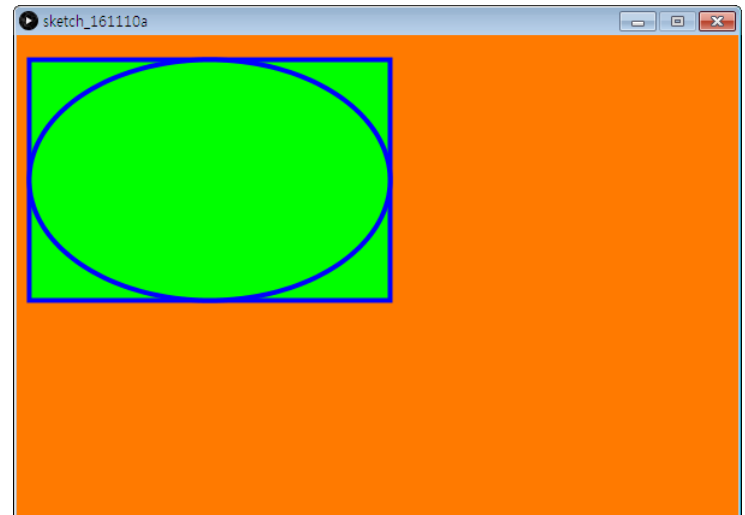
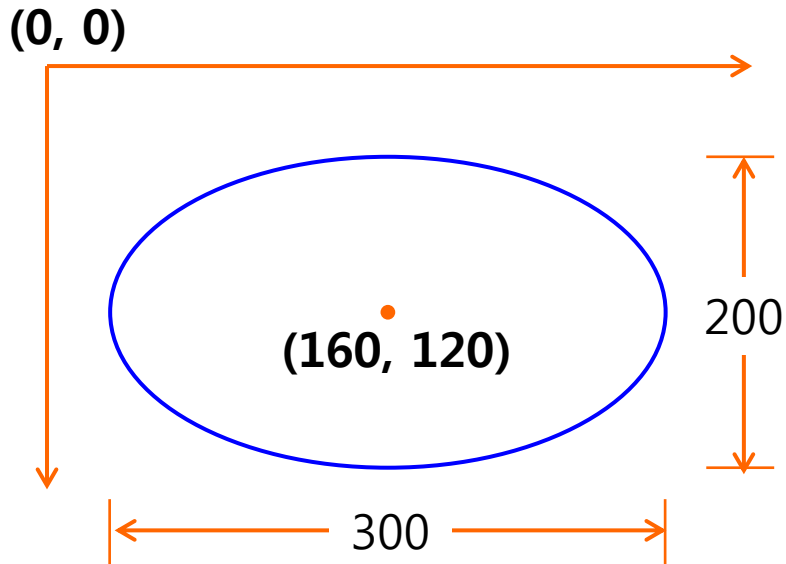
```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
noFill();  
rect(10, 20, 300, 200);
```



타원 그리기

```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
rect(10, 20, 300, 200);  
ellipse(160, 120, 300, 200);
```

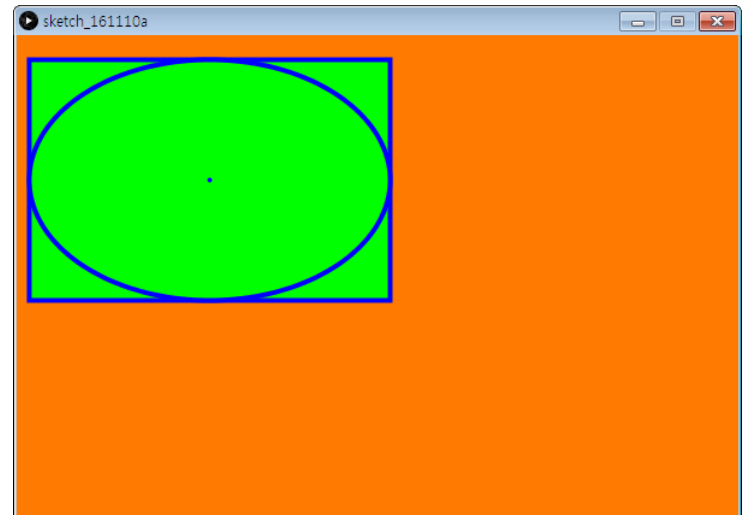
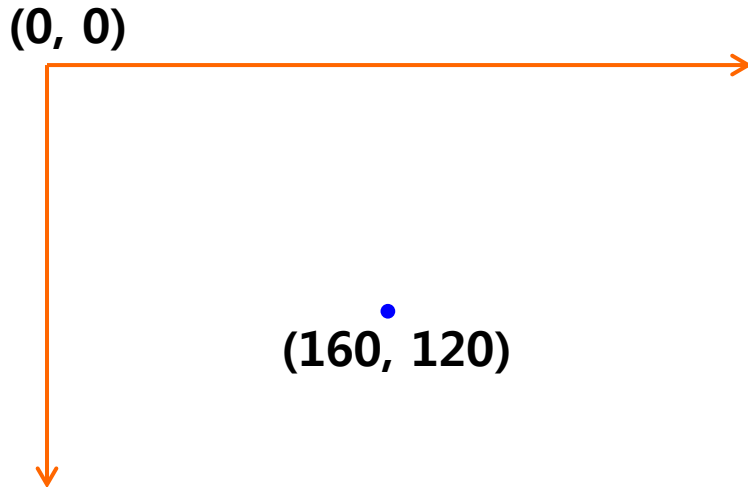
폭 높이



점 그리기

12

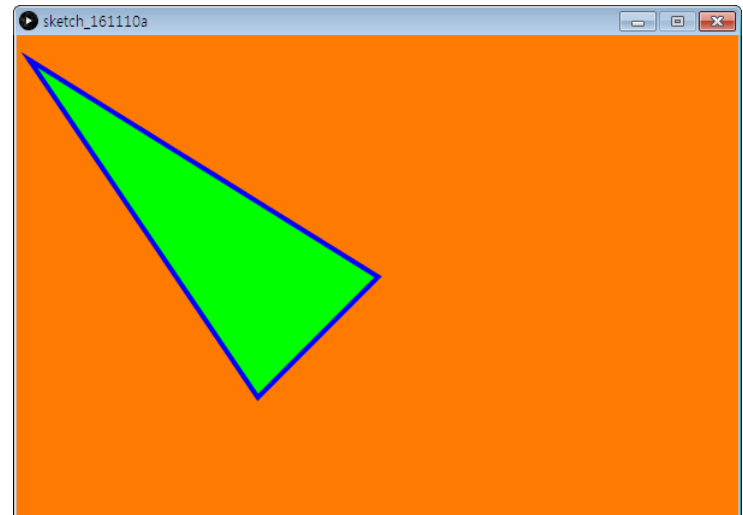
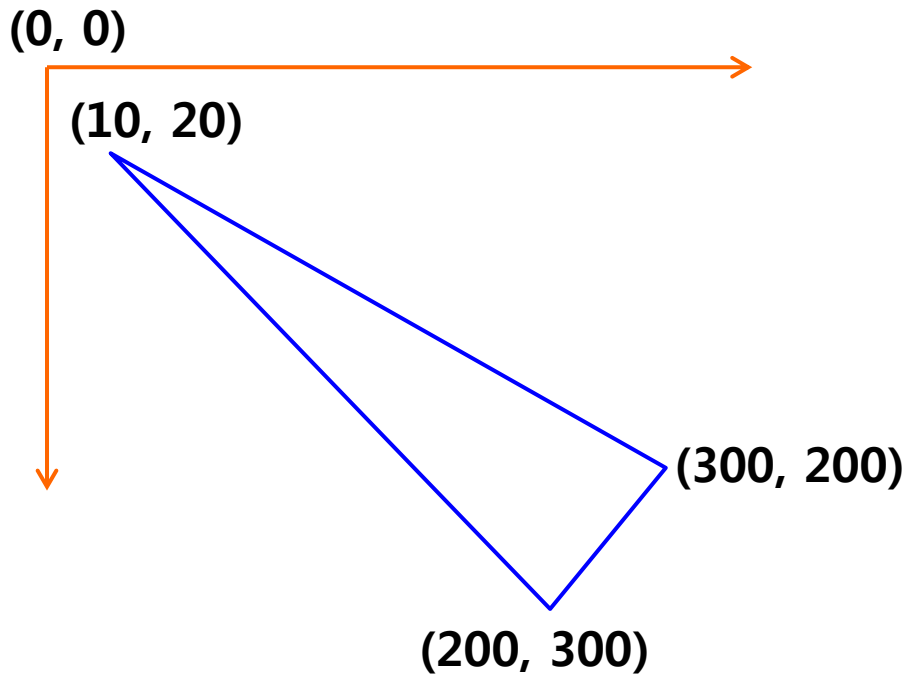
```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
rect(10, 20, 300, 200);  
ellipse(160, 120, 300, 200);  
point(160, 120);
```



삼각형 그리기

13

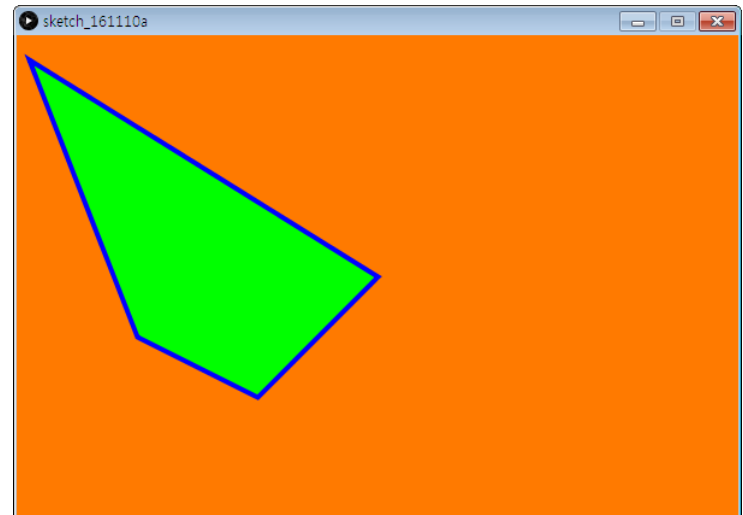
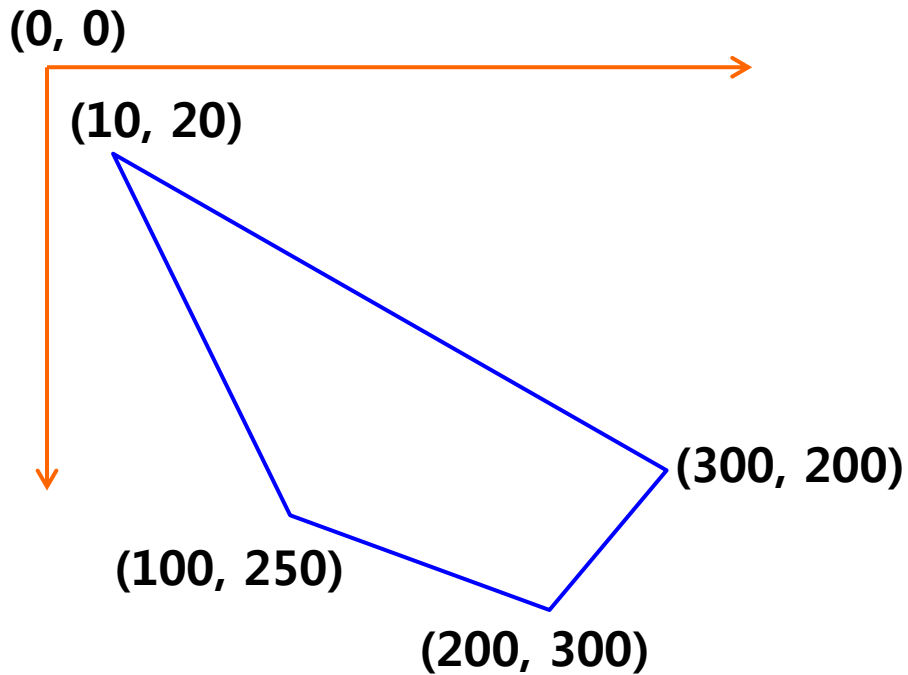
```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
triangle(10, 20, 300, 200, 200, 300);
```



사각형 그리기

14

```
size(600, 400);  
background(255, 122, 0);  
stroke(0, 0, 255);  
strokeWeight(4);  
fill(0, 255, 0);  
quad(10, 20, 300, 200, 200, 300, 100, 250);
```



애니메이션

```
void setup() {  
  
}  
  
void draw() {  
  
}
```

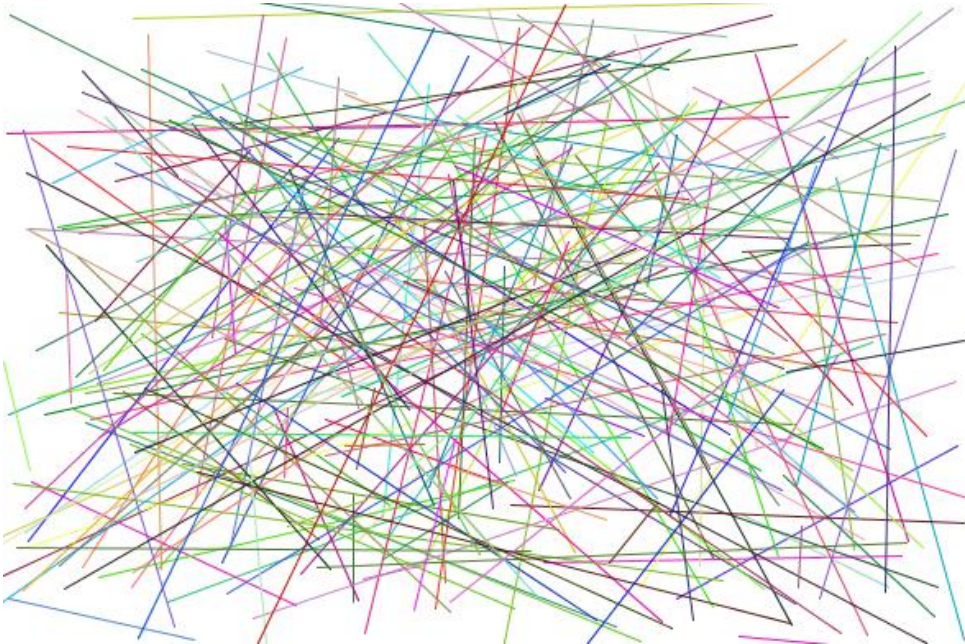


```
void setup() {  
  size(600, 400);  
  background(255, 122, 0);  
  stroke(0, 0, 255);  
}  
  
void draw() {  
  int c = frameCount % 256;  
  fill(c, 0, 0);  
  rect(10, 20, 300, 200);  
}
```



1부터 시작
draw() 호출하고 1씩 증가

```
void setup() {  
  size(600, 400);  
  background(255, 255, 255);  
}  
  
void draw() {  
  stroke(random(256), random(256), random(256));  
  line(random(width), random(height), random(width), random(height));  
}
```



- `random(end);`
- `random(start, end);`

↙
end는 포함 안 됨

```
void setup() {  
  size(600, 400);  
  background(255);  
  stroke(0, 0, 255);  
}  
  
void draw() {  
  line(200, 200, mouseX, mouseY);  
}
```

→ background(255, 255, 255)
와 같음

```
void setup() {  
  size(600, 400);  
  stroke(0, 0, 255);  
}  
  
void draw() {  
  background(255);  
  line(200, 200, mouseX, mouseY);  
}
```

```
void setup() {  
    size(600, 400);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    line(200, 200, mouseX, mouseY);  
}  
  
void mousePressed() {  
    background(255);  
}
```

```
void setup() {  
    size(600, 400);  
    stroke(0, 0, 255);  
}  
  
void draw() {  
    line(200, 200, mouseX, mouseY);  
}  
  
void mousePressed() {  
    if(mouseButton == LEFT)  
        background(255);  
    else  
        background(255, 122, 0);  
}
```

- `mouseButton`
- `mouseClicked()`
- `mouseDragged()`
- `mouseMoved()`
- `mousePressed()`
- `mouseReleased()`
- `mouseWheel()`
- `mouseX`
- `mouseY`
- `pmouseX`
- `pmouseY`

```
void setup() {  
  size(600, 400);  
  background(255);  
  stroke(0, 0, 255);  
}  
  
void draw() {  
}  
  
void mouseDragged() {  
  line(pmouseX, pmouseY, mouseX, mouseY);  
}
```

```
void setup() {  
  size(600, 400);  
  background(255);  
  stroke(0, 0, 255);  
  fill(0, 255, 0);  
}  
  
void draw() {  
  background(255);  
  rect(mouseX, mouseY, 30, 30);  
}
```

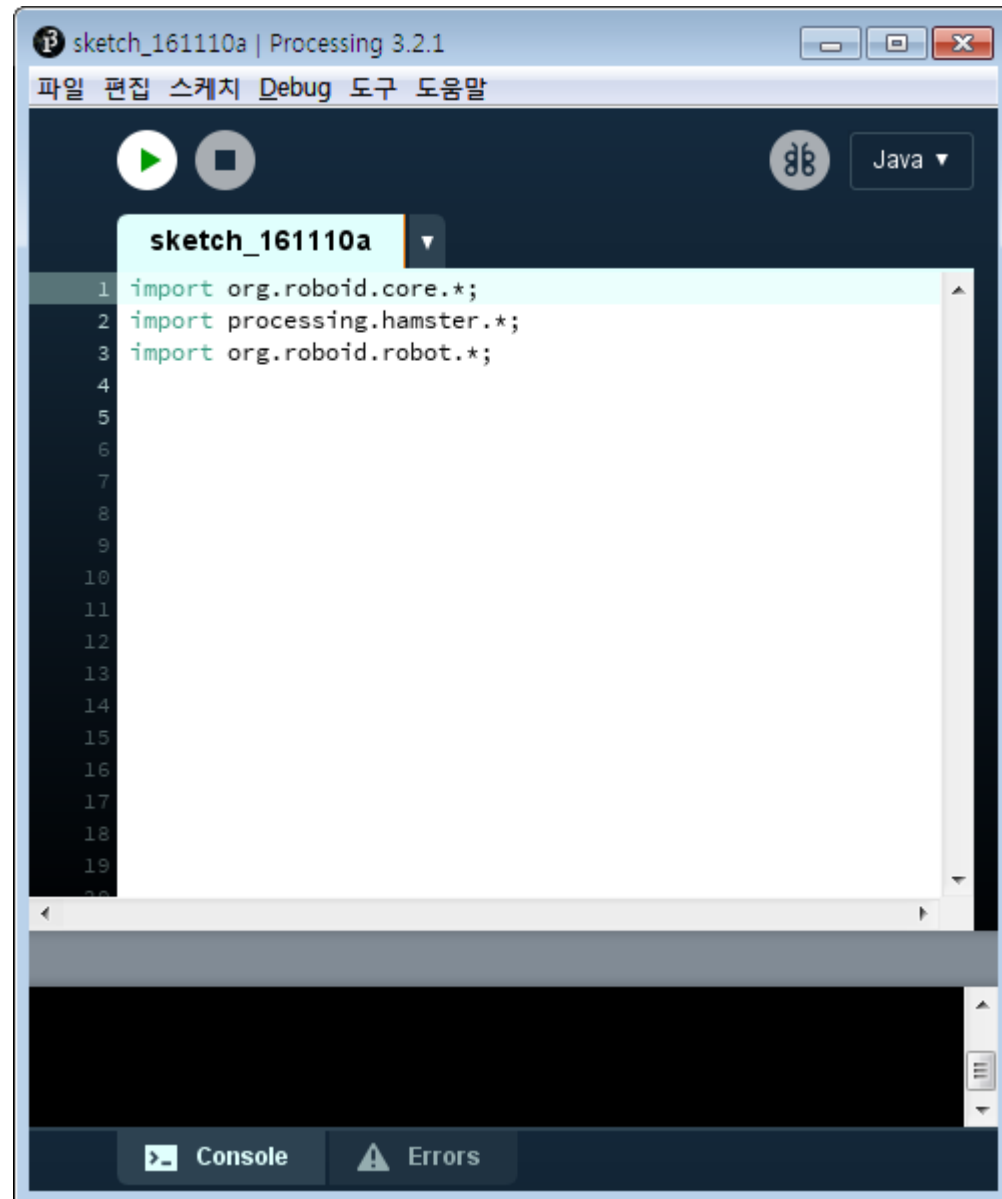


```
void setup() {  
  size(600, 400);  
  background(255);  
  stroke(0, 0, 255);  
}  
  
void draw() {  
  line(200, 200, mouseX, mouseY);  
}  
  
void keyPressed() {  
  if(key == 'a')  
    background(255);  
  else  
    background(255, 122, 0);  
}
```

- `key`
- `keyCode`
- `keyPressed()`
- `keyPressed`
- `keyReleased()`
- `keyTyped()`

햄스터

- 스케치
 - > 내부 라이브러리...
 - > Roboid



1초 앞으로 이동하기

29

```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  hamster.wheels(30, 30);
  delay(1000);
  hamster.stop();
}
```



왼쪽 바퀴 속도 (-100 ~ 100) %

오른쪽 바퀴 속도 (-100 ~ 100) %

msec (1000분의 1초 단위)

1초 뒤로 이동하기

30

```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  hamster.wheels(-30, -30);
  delay(1000);
  hamster.stop();
}
```



제자리 돌기 (스핀)

31

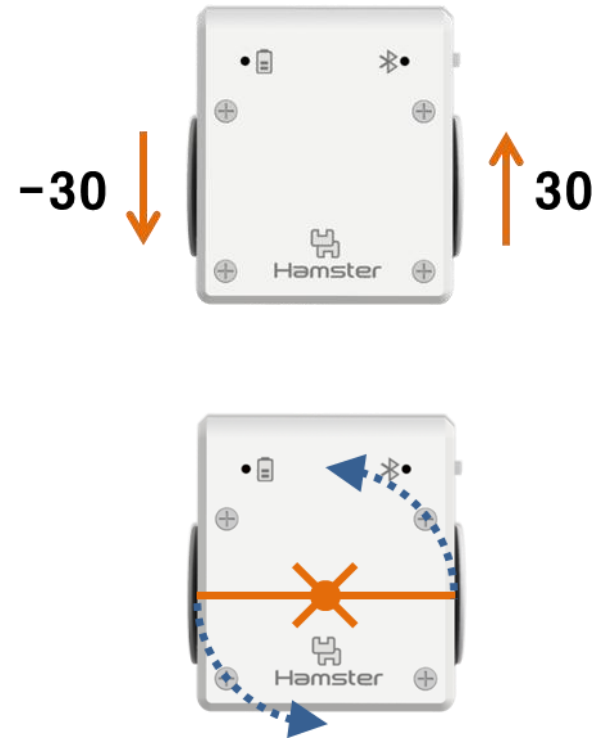
```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  hamster.wheels(-30, 30);
  delay(1000);
  hamster.stop();
}
```



한쪽 바퀴를 축으로 회전하기 (피봇 턴)

32

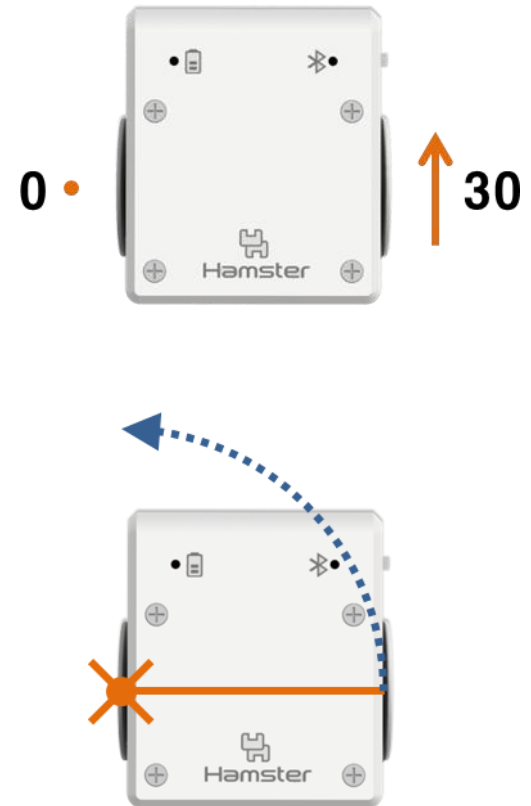
```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  hamster.wheels(0, 30);
  delay(1000);
  hamster.stop();
}
```



둥글게 회전하기 (라운드 턴)

33

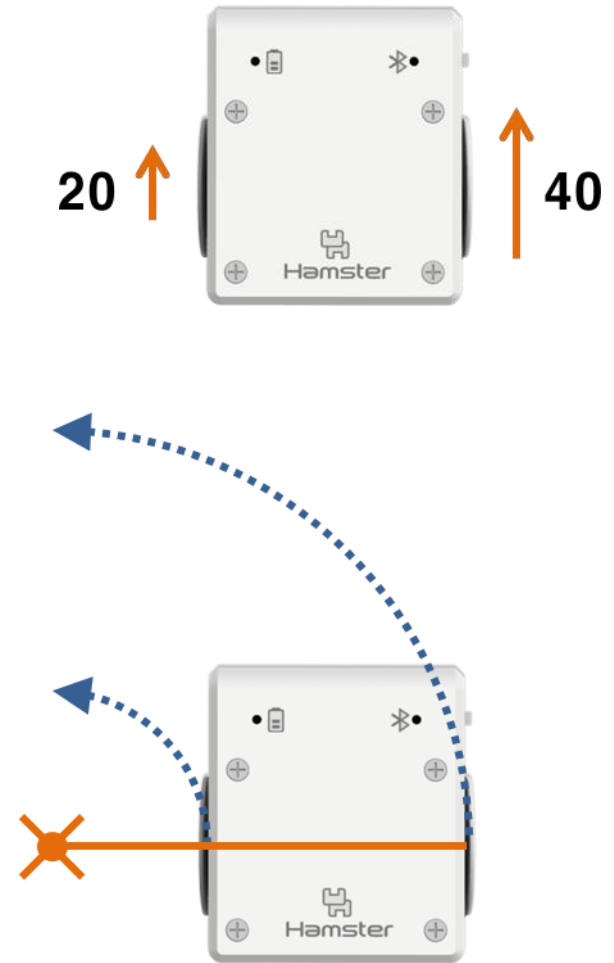
```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  hamster.wheels(20, 40);
  delay(1000);
  hamster.stop();
}
```



근접 센서 값 관찰하기

34

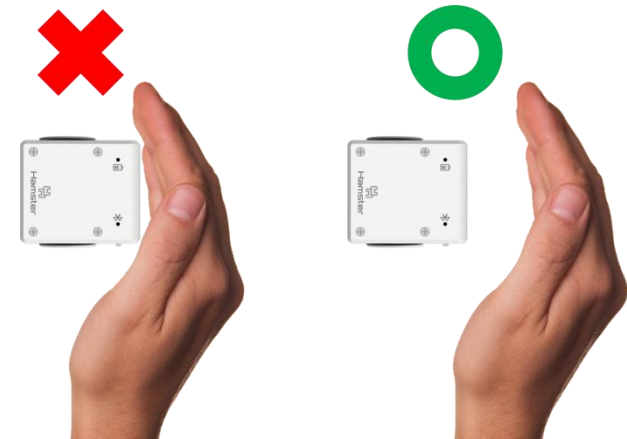
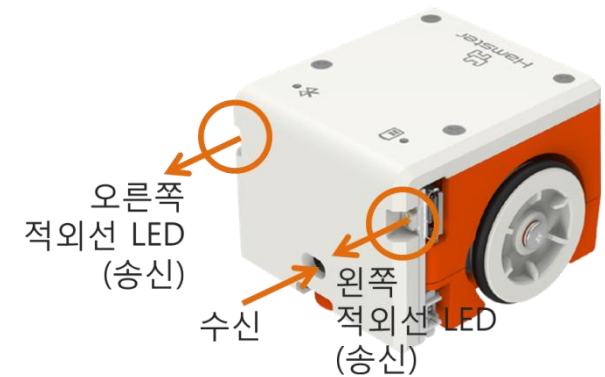
```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  while(true) {
    println(hamster.leftProximity());
    delay(20);
  }
}
```



```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;


void setup() {
  hamster = Hamster.create(this);
}

void draw() {
}

void run() {
  while (hamster.leftProximity() < 50) {
    delay(20);
  }
  hamster.wheels(-30, -30);
}
```

```
...  
  
void run() {  
    while(true) {  
        if(hamster.leftProximity() > 40) {  
            hamster.wheels(-30, -30);  
        } else {  
            hamster.wheels(30, 30);  
        }  
        delay(20);  
    }  
}
```

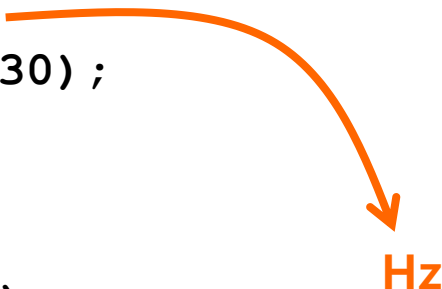
```
...  
  
void run() {  
  while(true) {  
    if(hamster.leftProximity() > 40) {  
      hamster.leds(Hamster.LED_RED, Hamster.LED_RED);  
      hamster.wheels(-30, -30);  
    } else {  
      hamster.leds(0, 0);  
      hamster.wheels(30, 30);  
    }  
    delay(20);  
  }  
}
```



왼쪽 LED 색깔

오른쪽 LED 색깔

```
...  
  
void run() {  
  while(true) {  
    if(hamster.leftProximity() > 40) {  
      hamster.leds(Hamster.LED_RED, Hamster.LED_RED);  
      hamster.buzzer(1000);  
      hamster.wheels(-30, -30);  
    } else {  
      hamster.leds(0, 0);  
      hamster.buzzer(0);  
      hamster.wheels(30, 30);  
    }  
    delay(20);  
  }  
}
```



Hz

햄스터 + 그래픽

```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
    hamster = Hamster.create(this);
}

void draw() {
}
```

```
void keyPressed() {
    if(key == ' ')
        hamster.stop();
    else if(key == CODED) {
        if(keyCode == UP)
            hamster.wheels(30, 30);
        else if(keyCode == DOWN)
            hamster.wheels(-30, -30);
        else if(keyCode == LEFT)
            hamster.wheels(-30, 30);
        else if(keyCode == RIGHT)
            hamster.wheels(30, -30);
    }
}
```



```
import org.roboid.core.*;
import processing.hamster.*;
import org.roboid.robot.*;

Hamster hamster;

void setup() {
  size(200,200);
  hamster = Hamster.create(this);
}

void draw() {
  background(255);
  fill(0);
  ellipse(100,100, 30, 30);
  line(100 ,100, mouseX, mouseY);
}
```

```
void run() {
  while(true) {
    if(mousePressed) {
      int dx = (100 - mouseX) / 2;
      int dy = (100 - mouseY) / 2;

      if(dy < 0)
        hamster.wheels(dy + dx, dy - dx);
      else
        hamster.wheels(dy - dx, dy + dx);
    } else {
      hamster.stop();
    }
    delay(20);
  }
}
```

수고하셨습니다.

<http://hamster.school>

akaii@kw.ac.kr